



Pullback approach for gyrokinetic electromagnetic simulations

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Acknowledgements: P. Helander, F. Jenko, F. Zonca

This work has been carried out within the framework of the EUROfusion Consortium and has received funding from the Euratom research and training programme 2014-2018 under grant agreement No 633053. The views and opinions expressed herein do not necessarily reflect those of the European Commission.





• Kinetic effects on MHD instabilities

- Finite ion gyroradius (e.g. comparable to boundary layer width kink)
- Finite electric field (electron inertia, electron pressure, collisionality)
- Non-fluid "compressibility": trapped-particle effect (kink, ballooning)
- Kinetic destabilisation of MHD-stable modes
 - Fast-ion destabilisation of Alfvén eigenmodes: TAE, HAE, GAE, BAE
 - Lower MHD destabilisation thresholds: KBM
 - Interaction between (marginal) MHD and fast ions: fishbones
- EM microturbulence: global profile evolution (drift-Alfvén)
 - Global approach is needed (intrinsic for MHD; needed for profiles)
 Kinetic approach is needed (to address relevant physics)







 $\epsilon_B = r_{
m g}/L_B \ll 1$

$$\epsilon = \omega/\omega_c \sim k_\parallel/k_\perp \sim q\delta\phi/T \sim \delta B/B \ll 1$$

Perturbative elimination of fast gyro-scale \Rightarrow **Gyrokinetics**





- 1995: GYGLES is developed at SPC(CRPP) with adiabatic electrons
- 1997: kinetic electrons implemented in GYGLES at IPP
- 1999: ORB5 is developed at SPC
- 1999: EUTERPE is developed at SPC
- 2004: EUTERPE implemented for W7-X at IPP
- 2004: GYGLES becomes electromagnetic at IPP
- 2008: ORB5 becomes electromagnetic, joint development IPP/SPC/UW
- 2009: EUTERPE becomes electromagnetic at IPP

All the codes share the equations solved, physics addressed and the discretisation principles applied. Deeper core routines are often very similar. Normalisation in EUTERPE and ORB5 is almost identical.





$$egin{aligned} &\gamma = qec{A}^*(ec{R})\cdot\mathrm{d}ec{R} + rac{m}{q}\mu\mathrm{d} heta - \left(rac{mv_\parallel^2}{2} + \mu B
ight)\mathrm{d}t + qA_\parallel(ec{x})ec{b}\cdot\mathrm{d}ec{x} - q\phi(ec{x})\mathrm{d}t \ &ec{A}^* = ec{A}_0 + rac{mv_\parallel}{q}ec{b} \ , \ ec{x} = ec{R} + ec{
ho}(heta) \end{aligned}$$

- $ec{x} = ec{R} + ec{
 ho}(heta) \Rightarrow$ gyro-dependent correction is not small, when $k_{\perp}
 ho \geq 1$
- Eliminate fast gyro-phase dependence from the Lagrangian
- USE LIE TRANSFORM: $\Gamma = e^{\hat{G}}\gamma + dS$

$$\begin{split} \underline{p_{\parallel} - GK} : \Gamma &= q\vec{A^*}\mathrm{d}\vec{R} + \frac{B}{\Omega}\mu d\theta - \left(\frac{mv_{\parallel}^2}{2} + \mu B + q\langle\phi\rangle - qv_{\parallel}\langle A_{\parallel}\rangle\right)\mathrm{d}t\\ \underline{v_{\parallel} - GK} : \Gamma &= q\vec{A^*}\mathrm{d}\vec{R} + \frac{B}{\Omega}\mu d\theta + \langle A_{\parallel}\vec{b}\rangle\mathrm{d}\vec{R} - \left(\frac{mv_{\parallel}^2}{2} + \mu B + q\langle\phi\rangle\right)\mathrm{d}t \end{split}$$

T. S. Hahm (1988), A. J. Brizard (1988, 1994, 2000)





method of characteristics • Gyrokinetic Vlasov equation: $rac{\partial f_{1s}}{\partial t} + ec{R} \cdot rac{\partial f_{1s}}{\partial ec{R}} + \dot{v}_{\parallel} rac{\partial f_{1s}}{\partial v_{\parallel}} = -ec{ec{R}^{(1)}} \cdot rac{\partial F_{0s}}{\partial ec{R}} - \dot{v}_{\parallel}^{(1)} rac{\partial F_{0s}}{\partial v_{\parallel}}$ • Gyrocenter trajectories: $\partial \langle A_{\parallel} \rangle / \partial t$ appears in v_{\parallel} -GK! $ec{R} \dot{ec{R}} = v_{\parallel}ec{b^{st}} + rac{1}{q_s ilde{B}_{\parallel}^*}ec{b} imes \left| \mu
abla B + q_s \left(
abla \langle \phi
angle + rac{\partial \left\langle A_{\parallel}
ight
angle}{\partial t} ec{b}
ight)
ight|$ $\dot{v}_{\parallel} = -rac{1}{m_s}ec{b^*}\cdot\mu
abla B - rac{q_s}{m_s}\left(ec{b^*}\cdot
abla\,\langle\phi
angle + rac{\partialig\langle A_{\parallel}ig
angle}{\partial t}
ight)$ $ec{B^*} = ec{B} + rac{m_s}{\hat{s}} v_{\parallel s} (
abla imes ec{b}) + ec{b} \cdot
abla imes A_{\parallel} ec{b} = B_{\parallel}^* + ec{b} \cdot
abla imes A_{\parallel} ec{b}$ • Gyrokinetic field equations: $\delta_{gv} = \delta(\vec{R} + \rho - \vec{x})$

$$\sum_{s=i,f}\int rac{q_s^2F_{0s}}{T_s}\left(\phi-\langle\phi
angle
ight)\delta_{\mathrm{gy}}\,\mathrm{d}^6Z=\sum_{s=i,e,f}q_sar{n}_s\,,\quad -
abla_\perp^2A_\parallel=\mu_0\sum_{s=i,e,f}ar{j}_{\parallel s}\,,$$





- Gyrokinetic Vlasov equation: method of characteristics $\frac{\partial f_{1s}}{\partial t} + \dot{\vec{R}} \cdot \frac{\partial f_{1s}}{\partial \vec{R}} + \dot{v}_{\parallel} \frac{\partial f_{1s}}{\partial v_{\parallel}} = -\dot{\vec{R}}^{(1)} \cdot \frac{\partial F_{0s}}{\partial \vec{R}} - \dot{v}_{\parallel}^{(1)} \frac{\partial F_{0s}}{\partial v_{\parallel}}.$ • Gyrocenter trajectories: $\partial \langle A_{\parallel} \rangle / \partial t$ does not appear in p_{\parallel} -GK! $\vec{\vec{R}} = \left(v_{\parallel} - \frac{q}{m} \langle A_{\parallel} \rangle \right) \vec{b}^{*} + \frac{1}{qB_{\parallel}^{*}} \vec{b} \times \left[\mu \nabla B + q \left(\nabla \langle \phi \rangle - v_{\parallel} \nabla \langle A_{\parallel} \rangle \right) \right]$ $\dot{v}_{\parallel} = -\frac{1}{m} \left[\mu \nabla B + q \left(\nabla \langle \phi \rangle - v_{\parallel} \nabla \langle A_{\parallel} \rangle \right) \right] \cdot \vec{b}^{*}$
- Gyrokinetic field equations:

$$egin{aligned} &\int rac{q_i F_{0i}}{T_i} \left(\phi - \langle \phi
angle
ight) \delta(ec{R} +
ho - ec{x}) \, \mathrm{d}^6 Z = ar{n}_i - ar{n}_e \ &rac{eta_i}{
ho_i^2} \langle \overline{A}_\parallel
angle_i + rac{eta_e}{
ho_e^2} A_\parallel -
abla_\perp^2 A_\parallel = \mu_0 \left(ar{j}_{\parallel i} + ar{j}_{\parallel e}
ight) \end{aligned}$$





• "Klimontovich" representation for perturbed distribution function:

$$\delta f_s(ec{R},v_\parallel,\mu,t) = \sum_{
u=1}^{N_p} w_{s
u}(t) \delta(ec{R}-ec{R}_
u) \delta(v_\parallel-v_{
u\parallel}) \delta(\mu-\mu_
u) \ ,$$

• Maxwellian distribution for all species:

$$F_{0s} = n_0 \left(rac{m}{2\pi T_s}
ight)^{3/2} \exp\left[-rac{m_s v_\parallel^2}{2T_s}
ight] \exp\left[-rac{m_s v_\perp^2}{2T_s}
ight]$$

• Finite-element discretization for fields:

$$\phi(ec x) = \sum_{l=1}^{N_s} \phi_l(t) \Lambda_l(ec x) \ , \quad A_\parallel(ec x) = \sum_{l=1}^{N_s} a_l(t) \Lambda_l(ec x) \ ,$$







• Very large skin terms are "generated" by p_{\parallel} -formulation: Not physics!

$$rac{eta_e}{
ho_e^2}A_\parallel=rac{\mu_0n_0e^2}{m_e}A_\parallel$$

• Adiabatic currents are "generated" by p_{\parallel} -formulation: Not physics!

 $ar{H}_1 = q_s \left(\langle \phi
angle_s - oldsymbol{v}_\parallel \langle oldsymbol{A}_\parallel
angle_s
ight) \;, \;\;\; F_e^{(\mathrm{ad})} = F_{0e} \, e^{-ar{H}_1/T_e} pprox - rac{q_e F_{0e}}{T_o} \left(\phi - oldsymbol{v}_\parallel oldsymbol{A}_\parallel
ight)$

Adiabatic current coincides with the skin terms
 <u>Must cancel each other!</u>

$$\mu_0 ar{j}_{\parallel s}^{(\mathrm{ad})} = \mu_0 q_s \int v_\parallel F_s^{(\mathrm{ad})} \mathrm{d}^3 v = rac{\mu_0 n_0 e^2}{m_e} A_\parallel = rac{eta_e}{
ho_e^2} A_\parallel$$



• True-particle distribution function f_s can be expressed through gyrokinetic $\overline{f_s}$ by p_{\parallel} -transform: Also in quasineutrality!

$$f_{1s} = ar{f_{1s}} + egin{array}{c} rac{m{q}_s \langle A_\parallel
angle}{m{m}_s} rac{\partial F_{0s}}{\partial v_\parallel} + \{S_1,F_{0s}\} \ , \quad \omega_{ ext{cs}} rac{\partial S_1}{\partial heta} = m{q}_s \Big(\widetilde{\phi} - v_\parallel \widetilde{A}_\parallel \Big) \ , \quad \omega_{ ext{cs}} rac{\partial S_1}{\partial heta} = m{q}_s \Big(\widetilde{\phi} - v_\parallel \widetilde{A}_\parallel \Big)$$

Ampere's law in terms of the true-particle distribution function

$$\underbrace{-
abla_{\perp}^2 A_{\parallel}}_{ ext{grid}} = \underbrace{\mu_0 \int v_{\parallel} \left[ar{f}_{1s} + rac{oldsymbol{q}_s \langle A_{\parallel}
angle}{oldsymbol{m}_s} rac{\partial F_{0s}}{\partial v_{\parallel}}
ight] \, \delta(ec{R} + ec{
ho} - ec{x}) \mathrm{d}^6 Z}_{ ext{particles}}$$

• Discretize skin terms with particles in Ampere's law and quasineutrality

$$ar{f}_{1s}(Z) = \sum_{
u=1}^{N_p} w_
u \delta(Z-Z_
u(t)) \ , \quad F_{0s}(Z) = \sum_{
u=1}^{N_p} F_{0s}(Z_
u) \zeta_
u \delta(Z-Z_
u(t))$$





• Split the magnetic potential into the 'symplectic' and 'Hamiltonian' parts:

$$A_\parallel = A_\parallel^{
m (s)} + A_\parallel^{
m (h)}$$

• The perturbed guiding-center phase-space Lagrangian

$$\gamma = qec{A^*} \cdot \mathrm{d}ec{R} + rac{m}{q} \, \mu \, \mathrm{d} heta + q \, A_\parallel^{(\mathrm{s})} ec{b} \cdot \mathrm{d}ec{x} + q \, A_\parallel^{(\mathrm{h})} ec{b} \cdot \mathrm{d}ec{x} - \left[rac{m v_\parallel^2}{2} + \mu B + q \phi
ight] \mathrm{d}t$$

• "Mixed" Lie transform: $A_{\parallel}^{(\mathrm{h})} o$ Hamiltonian, $A_{\parallel}^{(\mathrm{s})} o$ symplectic structure

$$\Gamma = qec{A^*} \cdot \mathrm{d}ec{R} + rac{m}{q} \mu \,\mathrm{d} heta + q \Big\langle A^{(\mathrm{s})}_{\parallel} \Big
angle \cdot \mathrm{d}ec{R} - \left[rac{m v_{\parallel}^2}{2} + \mu B + q \Big\langle \phi - v_{\parallel} A^{(\mathrm{h})}_{\parallel} \Big
angle
ight] \mathrm{d}t$$





• The corresponding perturbed equations of motion are

$$egin{aligned} \dot{ec{R}}^{(1)} &= rac{ec{b}}{B_{\parallel}^{*}} imes
abla &igg< egin{aligned} \dot{ec{R}}^{(1)} &= -rac{ec{b}}{m} \left< ec{\phi} - ec{v}_{\parallel} A_{\parallel}^{(ext{s})}
ight> - ec{v}_{\parallel} A_{\parallel}^{(ext{h})}
ight> - rac{ec{q}}{m} \left< A_{\parallel}^{(ext{h})}
ight> ec{b}^{*} \ \dot{ec{b}}^{*} \ \dot{ec{v}}_{\parallel}^{(1)} &= -rac{ec{q}}{m} \left[ec{b}^{*} \cdot
abla & igo\langle \phi - ec{v}_{\parallel} A_{\parallel}^{(ext{h})}
ight> + rac{\partial}{\partial t} \left< A_{\parallel}^{(ext{s})}
ight>
ight] - rac{\mu}{m} rac{ec{b} imes
abla B_{\parallel}^{*} \ \dot{ec{b}} \cdot
abla \left< A_{\parallel}^{(ext{s})}
ight> \end{aligned}$$

• An equation for $\partial A_{\parallel}^{(\mathrm{s})}/\partial t$ is needed

$$rac{\partial}{\partial t} A^{(\mathrm{s})}_{\parallel} + ec{b} \cdot
abla \phi = 0$$

• Ampere's law takes the form

$$\sum_{s=i,e,f} rac{eta_s}{
ho_s^2} \Big\langle \overline{A}_\parallel^{(\mathrm{h})} \Big
angle_s -
abla_\perp^2 A_\parallel^{(\mathrm{h})} = \mu_0 \sum_{s=i,e,f} j_{\parallel 1s} +
abla_\perp^2 A_\parallel^{(\mathrm{s})}$$





$$egin{aligned} f_{1s}(Z_s,A_\parallel^{(s)}) &= f_{1m}(Z_m,A_\parallel^{(s)},A_\parallel^{(h)}) \ v_\parallel^{(\mathrm{s})} &= v_\parallel^{(\mathrm{m})} - rac{e}{m} \left\langle A_\parallel^{(\mathrm{h})}
ight
angle \end{aligned}$$

Additional nonlinear terms appear in equations of motion [R. Kleiber et al, PoP 2016] (symplectic-hamiltonian equivalence at the 2nd order)

- 1. Push coordinates and weights in mixed-variable space (nonlinear)
- 2. Transform coordinates into symplectic space keeping weights constant 3. Set $A_{\parallel(\text{new})}^{(s)}(t_i) = A_{\parallel}(t_i) = A_{\parallel(\text{old})}^{(s)}(t_i) + A_{\parallel(\text{old})}^{(h)}(t_i)$ and $A_{\parallel(\text{new})}^{(h)}(t_i) = 0$.

Conservation laws in mixed-variable gyrokinetics



A gyrokinetic field theory is obtained from action principle

$$\delta \mathcal{A} = \delta \int_{t_1}^{t_2} \mathcal{L} \, \mathrm{d}t = 0$$

where ${\boldsymbol{\mathcal{A}}}$ is called the action and ${\boldsymbol{\mathcal{L}}}$ the Lagrangian

$$\mathcal{L}[ec{R}, U_{\parallel}, \mu, lpha, \phi, A^s_{\parallel}, A^h_{\parallel}] = \sum_{\sigma} \int \mathrm{d}W_0 \mathrm{d}V_0 f_{\sigma,0}(\mathrm{Z}_0) L_{\sigma}(\mathrm{Z}, \dot{\mathrm{Z}})
onumber \ + \int \mathrm{d}V rac{q_i
ho_i^2}{k_\mathrm{B} T_i} |
abla_{\perp} \phi|^2 - rac{1}{2\mu_0} \int \mathrm{d}V |
abla_{\perp} A_{\parallel}|^2 + \int \mathrm{d}V \lambda \left(rac{\partial A^s_{\parallel}}{\partial t} + ec{b} \cdot
abla \phi
ight)$$

GK single-particle Hamiltonian and Lagrangian are

$$egin{aligned} H_{\sigma} &= rac{m U_{\parallel}^2}{2} + \mu B(ec{R}) + q_{\sigma}(\langle \phi
angle - U_{\parallel} \langle A^h_{\parallel}
angle) + rac{q_{\sigma}^2}{2m_{\sigma}} \langle A^h_{\parallel}
angle^2 - rac{q_i
ho_i^2}{2T_i(ec{R})}
abla_{\perp} |\phi|^2 \ L_{\sigma}(ec{R}, U_{\parallel}, \mu, \dot{ec{R}}, \dot{lpha}) &= q_{\sigma} ec{A}^{\star}_{\sigma} \cdot \dot{ec{R}} + rac{m_{\sigma}^2}{q_{\sigma}} \mu \dot{lpha} - H_{\sigma} \end{aligned}$$

Liouville theorem follows from variational principle:

$$rac{\partial B^{\star}_{\parallel,\sigma}}{\partial t} +
abla \cdot \left(B^{\star}_{\parallel,\sigma} \, rac{\mathrm{d} ec{R}}{\mathrm{d} t}
ight) + rac{\partial}{\partial U_{\parallel}} \left(B^{\star}_{\parallel,\sigma} \, rac{\mathrm{d} U_{\parallel}}{\mathrm{d} t}
ight) = 0$$

Thanks to the Liouville theorem the gyro-center distribution function of each particle species $f_{\sigma}(t, \vec{r}, u_{\parallel}, \tilde{\mu})$ satisfies the gyrokinetic Vlasov equation

$$rac{\mathrm{d} f_\sigma}{\mathrm{d} t} = rac{\partial f_\sigma}{\partial t} + rac{\mathrm{d} ec{R}}{\mathrm{d} t} \cdot
abla f_\sigma + rac{\mathrm{d} U_\parallel}{\mathrm{d} t} rac{\partial f_\sigma}{\partial u_\parallel} = 0$$

Lagrange multiplier for Ohm's law constrain satisfies:

$$\int \mathrm{d} V rac{\partial \lambda}{\partial t} ilde{A}_{\parallel} = 0 \hspace{0.4cm} orall ilde{A}_{\parallel} \hspace{0.2cm} \Rightarrow \hspace{0.2cm} rac{\partial \lambda}{\partial t} = 0$$

Taking zero as an initial condition for λ , which can be defined arbitrarily, Lagrange multiplier λ vanishes: $\lambda = 0$.





GK Lagrangian does not explicitly depend on time. There is a conserved energy related to Noether theorem:

$$rac{\mathrm{d}}{\mathrm{d}t} \left(\sum_\sigma \int \mathrm{d}W_0 \mathrm{d}V_0 f_{\sigma,0}(\mathrm{Z}_0) \left[rac{\partial L_\sigma}{\partial \dot{ec{R}}} \cdot \dot{ec{R}}
ight] - \mathcal{L}
ight) = 0$$

This implies that the following energy is conserved

$${\cal E}(t) = \sum_\sigma \int \mathrm{d} W_0 \mathrm{d} V_0 f_{\sigma,0}(\mathrm{Z}_0) H_\sigma - \int \mathrm{d} V rac{q_i
ho_i^2}{k_\mathrm{B} T_i} |
abla \phi|^2 + rac{1}{2\mu_0} \int \mathrm{d} V |
abla_\perp A_\parallel|^2$$

This energy is split into kinetic energy and potential energies.





$$\mathcal{E}_{ ext{pot}}(t) = rac{1}{2}\int \mathrm{d}V\left(qn\langle\phi
angle + j_{\parallel}\langle A^s_{\parallel}
angle - j_{\parallel}\langle A^h_{\parallel}
angle - \sum_{\sigma}rac{q^2_{\sigma}n_{\sigma}}{m_{\sigma}}\langle A^h_{\parallel}
angle\langle A^s_{\parallel}
angle
ight)$$

$$\mathcal{E}_{ ext{kin}} = \sum_{\sigma} \int \mathrm{d} W_0 \mathrm{d} V_0 f_{\sigma,0}(\mathrm{Z}_0) H_{\sigma,0} = \sum_{\sigma} \int \mathrm{d} u_{\parallel} \, \mathrm{d} \mu \, \mathrm{d} V f_{\sigma}(\mathrm{Z},t) \left[rac{m u_{\parallel}^2}{2} + \mu B(ec{R})
ight]$$

Energy conservation implies

$$egin{aligned} rac{\mathrm{d}\mathcal{E}_{\mathrm{kin}}}{\mathrm{d}t} &= -rac{\mathrm{d}\mathcal{E}_{\mathrm{pot}}}{\mathrm{d}t} = -\sum_{\sigma}\int\mathrm{d}u_{\parallel}\mathrm{d}\mu\mathrm{d}Vf_{\sigma}(\mathrm{z},t) \ &\left[rac{q_{\sigma}}{m_{\sigma}}\langle A^h_{\parallel}
angleec{B}_{\sigma}^{\star}\cdot
abla\langle \mu B+q_{\sigma}\langle\phi
angle-q_{\sigma}u_{\parallel}\langle A^h_{\parallel}
angle) \ &+B^{\star}_{\parallel,\sigma}\left(rac{q_{\sigma}}{m_{\sigma}}u_{\parallel}rac{\langle\partial A^s_{\parallel}
angle}{\partial t}+\dot{ec{R}}\cdot
abla\langle \phi
angle-q_{\sigma}u_{\parallel}\langle A^h_{\parallel}
angle)
ight)
ight] \end{aligned}$$





As the background fields do not depend on the toroidal angle in a tokamak, the total canonical angular momentum is conserved.

$$\delta \mathcal{L} = rac{\delta L}{\delta ec{R}} \cdot ec{R}_arphi = 0, \quad ext{ for } ec{R}_arphi = (0,0,R_arphi), \quad ext{with } R_arphi ext{ any constant.}$$

Knowing that the Euler-Lagrange equations are satisfied, yields

$$rac{\delta L}{\delta ec{R}} \cdot ec{R}_arphi = rac{\mathrm{d}}{\mathrm{d}t} \int \mathrm{d}W_0 \mathrm{d}V_0 f_{\sigma,0}(\mathrm{Z}_0) \left[rac{\partial L_\sigma}{\partial ec{R}} \cdot ec{R}_arphi
ight]$$

The conserved angular momentum in mixed-variable formulation is

$$\mathcal{P}_arphi = \sum_\sigma q_\sigma \int \mathrm{d}W \mathrm{d}V f_\sigma(\mathrm{z},t) \left[A_arphi + \left(rac{m_\sigma}{q_\sigma} u_\parallel + \langle A_\parallel^s
angle
ight) b_arphi
ight]$$





 f_0 is Maxwellian; $ec{B}_0 = B_0 ec{e}_z$, electrons are the only dynamical species,

$$\Phi, A_{\parallel}, \delta f \sim \exp\left[\mathrm{i}(k_{\perp}x+k_{\parallel}z)-\mathrm{i}\omega t
ight]$$

Linearized GK equations in v_{\parallel} -formulation:

$$egin{aligned} \dot{m{z}} = v_{\parallel} \,, \;\; \dot{v}_{\parallel}^{(1)} = & rac{q_{ ext{e}}}{m_{ ext{e}}} \left(rac{\partial \Phi}{\partial m{z}} + rac{\partial A_{\parallel}}{\partial m{t}}
ight) \,, \; rac{\partial \delta f_{ ext{e}}}{\partial m{t}} + v_{\parallel} rac{\partial \delta f_{ ext{e}}}{\partial m{z}} = & - \dot{v}_{\parallel}^{(1)} rac{\partial f_{e,0}}{\partial v_{\parallel}} \ & rac{m_{ ext{i}} n_0}{B^2} k_{\perp}^2 \Phi = q_{ ext{e}} \int \delta f_{ ext{e}} \, \mathrm{d} v_{\parallel} \,, \;\; k_{\perp}^2 A_{\parallel} = \mu_0 q_{ ext{e}} \int v_{\parallel} \delta f_{ ext{e}} \, \mathrm{d} v_{\parallel} \end{aligned}$$

Well-known exact dispersion relation ($v_{
m th,e}=\sqrt{2T_{
m e}/m_{
m e}}$, $ilde{\mu}=m_e/m_i$):

$$D_{ ext{exact}} = 1 - rac{2eta}{ar{k}_{\perp}^2} \left(ar{\omega}^2 - rac{ ilde{\mu}}{eta}
ight) \left(1 + ar{\omega}Z(ar{\omega})
ight) = 0$$

Consider kinetic shear Alfvén wave in slab geometry





Implicit Euler scheme with step-size Δt and $t = t_n = n\Delta t$

$$\left.rac{\partial A_{\parallel}}{\partial t}
ight|_{n}pprox rac{A_{\parallel,n}-A_{\parallel,n-1}}{\Delta t} = -\mathrm{i}\Omega_{+}A_{\,n}\,,~~\Omega_{\pm}=\pm\mathrm{i}rac{1-\mathrm{e}^{\pm\mathrm{i}\omega\Delta t}}{\Delta t}.$$

Equations of motions $z_n = z_{n-1} + v_{\parallel,n-1} \Delta t$ and $v_{\parallel,n} = {
m const}$,

$$\left. rac{\mathrm{d}\delta f_\mathrm{e}}{\mathrm{d}t}
ight|_n pprox rac{\delta f_{\mathrm{e},n} - \delta f_{\mathrm{e},n-1}}{\Delta t} = -\mathrm{i}K_+ f_{\mathrm{e},n} \ , \ \ K_\pm = \pm \mathrm{i}rac{1 - \mathrm{e}^{\pm \mathrm{i}(\omega - k_\parallel v_\parallel)\Delta t}}{\Delta t}$$

The numerical dispersion relation (converges to D_{exact} for $\Delta \overline{t} \rightarrow 0$)

$$egin{aligned} D_{v_{\parallel}} &= 1 - rac{2eta}{ar{k}_{\perp}^2} \sum_{l=-\infty}^\infty \left(ar{\Omega}_+ F_{1,l} - rac{ ilde{\mu}}{eta} F_{0,l}
ight) = 0 \ F_{0,l} &= \mathrm{e}^{-y^2 + 2\mathrm{i}xy} \left[1 + xZ(x + \mathrm{i}y)
ight] \ F_{1,l} &= \mathrm{e}^{-y^2 + 2\mathrm{i}xy} \left[x^2Z(x + \mathrm{i}y) + x - \mathrm{i}y
ight] \ x &= ar{\omega} - 2\pi l/\Deltaar{t}\,, \ y &= -\Deltaar{t}/4\,, \ ar{t} = tk_{\parallel}v_{\mathrm{th},e} \end{aligned}$$





The equations to be solved in this scheme are

$$\dot{z}=u_{\parallel}\,,~~\dot{u}_{\parallel}^{(0)}=0\,,~~\dot{u}_{\parallel}^{(1)}=rac{q_{ ext{e}}}{m_{ ext{e}}}u_{\parallel}rac{\partial A_{\parallel}^{ ext{h}}}{\partial z}\,,~~rac{ ext{d}\delta f_{ ext{e}}}{ ext{d}t}=-\dot{u}_{\parallel}^{(1)}rac{\partial f_{ ext{e},0}}{\partial u_{\parallel}}$$

with the field equations

$$\left(k_\perp^2+rac{\mu_0n_0q_{
m e}^2}{m_{
m e}}
ight)A_\parallel^{
m h}=\mu_0q_{
m e}\int u_\parallel\delta f_{
m e}\,{
m d} u_\parallel-k_\perp^2A_\parallel^{
m s}\,,\;\;rac{m_{
m i}n_0}{B^2}k_\perp^2\Phi=q_{
m e}\int\delta f\,{
m d} u_\parallel$$

Ohm's law

$$rac{\partial A^{
m s}_{\parallel}}{\partial t}=-rac{\partial \Phi}{\partial z}$$

and pullback transformation has to be applied at end of each time step

$$\delta f_{
m e}^* = \delta f_{
m e} + rac{q_{
m e}}{m_{
m e}} rac{\partial f_{
m e,0}}{\partial u_{\parallel}} A_{\parallel}^{
m h} \,, \;\; A_{\parallel}^{
m s*} = A_{\parallel}^{
m s} + A_{\parallel}^{
m h} \,, \;\; A_{\parallel}^{
m h} = 0$$





The transformed quantities have to be used for time derivatives:

$$\left. \frac{\partial A^{\mathrm{s}}_{\parallel}}{\partial t} \right|_{n} pprox rac{A^{\mathrm{s}}_{\parallel,n+1} - A^{\mathrm{s}*}_{\parallel,n}}{\Delta t}$$

Explicit Euler scheme with step-size Δt and $t = t_n = n\Delta t$.

$$\delta f_{\mathrm{e},n} = rac{\mathrm{i}}{\Delta t K_{-}} rac{q_{\mathrm{e}}}{m_{\mathrm{e}}} A^{\mathrm{h}}_{\parallel,n} rac{\partial f_{\mathrm{e},0}}{\partial u_{\parallel}} \,, \;\; A^{\mathrm{s}}_{\parallel,n} = rac{\mathrm{i}}{\Delta t \Omega_{-}} (A^{\mathrm{h}}_{\parallel,n} - \mathrm{i} k_{\parallel} \Phi_n \Delta t)$$

Important result $A^{
m h}_{\parallel}\sim\Delta t!$ Putting everything together leads finally to the numerical dispersion relation for the PT-scheme

$$D_{ ext{PT}} = 1 - \mathrm{i}ar{\Omega}_-\Delta t\left(1 + rac{eta}{ar{k}_\perp}
ight) - rac{2eta}{ar{k}_\perp^2}\sum_{l=-\infty}^\infty \left(ar{\Omega}_-F_{1,l} - rac{ ilde{\mu}}{eta}F_{0,l}
ight) = 0.$$

where $F_{0,l}, F_{1,l}$ now must be evaluated using $y = \Delta \overline{t}/4$.





- Explicit discretisation for the v_{\parallel} -scheme possible but leads to strong numerical instabilities.
- v_{\parallel} and PT-scheme give same results. Hence, both schemes are equivalent but PT-scheme is explicit.



- Ihh
- collisions important for realistic description of fusion plasmas
- electromagnetic simulations with EUTERPE including collisions had been unsuccessful in the past
- benchmark of EUTERPE against grid code based on decomposition of $f_e^{(1)}$ into Legendre polynomials (EF of pitch-angle collision operator)

$$rac{\partial f_e}{\partial t} + \dot{ec{R}} \cdot
abla f_e + \dot{u}_{\parallel} rac{\partial f_e}{\partial u_{\parallel}} = \mathcal{L}(f_e), \quad \mathcal{L}(f_e) = rac{
u}{2} rac{\partial}{\partial \xi} \left(1 - \xi^2\right) rac{\partial f_e}{\partial \xi}, \quad \xi = rac{v_{\parallel}}{v}$$
 $f_e^{(1)} = \sum_{l=0}^{N_l} f_l\left(u, t
ight) P_l\left(\xi'
ight) F, \quad P_l \dots l^{\mathsf{th}}$ Legendre polynomial

• kinetic Alfvén wave subject to electron pitch-angle collisions

J. W. Banks et al., Phys. Plasmas 23, 032108 (2016)





- real frequency not affected by collisions
- collisions lead to collisional damping for all $k_\perp
 ho_s$
- large $k_{\perp}
 ho_s$ (small scales) effectively damped by pitch-angle collisions
- EUTERPE and the Legendre approach agree very well
- stochastic scheme replaces Runge-Kutta: weaker convergence in Δt

C. Slaby et al., Comp. Phys. Comm. 218, 1-9 (2017)





SIMULATIONS

Toroidal Alfvén Eigenmode Energetic Particle Mode Internal Kink Mode Collisionless Tearing Mode Stellarators (EM drift modes)







Large-aspect-ratio, circular cross-sections Major radius $R_0 = 10$ m, minor radius $r_a = 1$ m Magnetic field on the axis $B_0 = 3.0$ T, flat density $n_0 = 2 \times 10^{19}$ m⁻³ Flat bulk-plasma temperature and density ($\beta_{\rm bulk} \approx 0.18\%$), Hydrogen Toroidal mode number n = 6







Radial pattern resulting from the PIC simulations (in some particular point of time)

It resembles a typical TAE structure.





Successful worldwide benchmark (ITPA framework) Linear with and without FLR Nonlinear (EUTERPE vs. ORB5; GK vs. reduced models)

Nonlinear mode structure (fast-particle nonlinearity) Mode saturation through resonance detuning and radial decoupling (Fulvio Zonca talk; this conference)

ITPA benchmark case (tokamak, n=-6 TAE) Fully GK simulations using EUTERPE DMUSIC algorithm (parametric method superior to FFT) GK DMUSIC spectrum compared with MHD continuum

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Dependency on the fast-particle temperature ($\beta_f = 0.134\%$ kept constant) Destabilization is most effective near the resonance $v_{thf} \approx v_A/3$ At large T_f , finite-orbit-width (FOW) stabilization is seen At smaller T_f (larger n_f to keep β_f constant), an EPM appears

Safety factor and SAW continuum

- Simulation Concept
 - Modify the ITPA benchmark parameter safety factor (magnetic shear)
 - But: use flat bulk plasma density and temperature (same v_A as ITPA)
- New physics (compared to ITPA)
 - The resulting continuum is much more complicated than ITPA
 - The gap is deformed and involves many modes; continuum resonances

- Electrostatic radial pattern at different times
- KAWs are excited at continuum resonances
- Resonantly excited KAWs mix with the global eigenmode (interference)
- Kinetic mode is wider comparing to ideal mode (KAW admixtures)

Internal kink mode (GYGLES)

Ideal-MHD internal kink mode equation:

$$rac{\mathrm{d}}{\mathrm{d}r}\left(\left[\underbrace{\mu_0 m_i n_0 \gamma^2}_{\mathrm{small}} + (ec{k} \cdot ec{B})^2
ight] r^3 rac{\mathrm{d}\xi}{\mathrm{d}r}
ight) - g(r) \xi = 0 \ , \quad \xi \propto \phi/r$$

- Intertial layer: plasma inertia can compete with magnetic tension
- Poloidal plasma rotation with $v_ heta \propto \partial \phi / \partial r$ resolves the MHD singularity
- ullet The width of the intertial layer $\lambda_H \propto \delta W_{
 m MHD}$
- "MHD regime": λ_H exceeds all microscopic kinetic scales (ρ_i , δ_e etc)

- Drift-kink mode: fine scale feature at resonant flux surface
- Sub-gyro scales are involved Kinetic Alfvén Waves (KAW) resonantly excited by the drift-kink mode
- Mode dynamics as a combination of MHD dynamics, reconnection and the KAW excitation ("continuum damping")

Internal kink mode in tokamak geometry ($R_0/r_a = 10$); strong MHD drive (pressure+current); GK-efluid comparison; fast-ion effect: MHD drive $p'_{\rm fast}$

KBM/ITG in LHD-like geometry (EUTERPE)

A. Mishchenko et al, Phys. Plasmas 21, 092110 (2014)

- Cancellation problem has prohibited large-scale effort on GK EM global PIC simulations (Reynders 1992, Cummings 1995)
- Reduced models have been widely used to circumvent the problem: hybrid kinetic-MHD, fluid-electron models
- Limitations of reduced models: closure issues, no micro-tearing physics
- A lot of work has been done to mitigate the cancellation problem: control variate, mixed-variable pullback scheme; US schemes
- The mitigation schemes can be used both in linear and nonlinear regimes
- The mitigation schemes have been validated on many examples, including the international ITPA benchmark

Global gyrokinetic EM PIC simulation schemes approach mainstream

1. At the end of each time step, redefine the magnetic potential splitting:

$$A^{(\mathrm{s})}_{\parallel(\mathrm{new})}(t_i) = A_{\parallel}(t_i) = A^{(\mathrm{s})}_{\parallel(\mathrm{old})}(t_i) + A^{(\mathrm{h})}_{\parallel(\mathrm{old})}(t_i)$$

- 2. As a consequence, redefine $A^{(\mathrm{h})}_{\parallel(\mathrm{new})}(t_i)=0$
- 3. New mixed-variable distribution function coincides with symplectic one (pullback 0-form): $f_1^{(s)}(Z^{(s)}, A_{\parallel}^{(s)}) = f_1^{(m)}(Z^{(m)}, A_{\parallel}^{(s)}, A_{\parallel}^{(h)})$

$$f_{1(\mathrm{new})}^{(\mathrm{m})}(t_i) = f_1^{(\mathrm{s})}(t_i) = f_{1(\mathrm{old})}^{(\mathrm{m})}(t_i) + rac{q \left\langle A_{\parallel(\mathrm{old})}^{(\mathrm{h})}(t_i)
ight
angle}{m} rac{\partial F_0}{\partial v_\parallel}$$

4. Proceed, explicitly solving the mixed-variable system of equations at the next time step $t_i + \Delta t$ in a usual way, but using the symplectic coordinates as the initial conditions.

Solution of the cancellation problem (iterative scheme)

• Ampere's law computes A_{\parallel} . But p_{\parallel} -transform depends on A_{\parallel} !

$$-
abla_{\perp}^2 A_{\parallel} = \mu_0 \int v_{\parallel} \left[ar{f}_{1s} + \{S_1, F_{0s}\} + rac{oldsymbol{q}_s \langle A_{\parallel}
angle}{oldsymbol{m}_s} rac{\partial F_{0s}}{\partial v_{\parallel}}
ight] \, \delta(ec{R} + ec{
ho} - ec{x}) \mathrm{d}^6 Z$$

- Solution: introduce an easy-to-compute estimator for transform (β_e/ρ_e^2) $(s+L)a = j \Rightarrow (s+L)a = j + (\hat{s} - \hat{s})a \Rightarrow (\hat{s} + L)a = j + (\hat{s} - s)a$
- Employ $\|\hat{s} s\| = \mathcal{O}(\epsilon)$ and solve Ampere's law iteratively $a = a_0 + \epsilon a_1 + \epsilon^2 a_2 + \dots, \quad (\hat{s} + L)a_0 = j, \quad (\hat{s} + L)a_1 = j + (\hat{s} - s)a_0, \dots$ $\hat{s}_{kl} = \int \frac{\beta_e}{\rho_e^2} \Lambda_k(\vec{x}) \Lambda_l(\vec{x}) \,\mathrm{d}^3 x, \quad j_k = \sum_{\nu=1}^{N_p} v_{\parallel\nu} \, w_\nu \langle \Lambda_k \rangle_
 u$ $j_k - s_{kl} a_l^{n-1} = \sum_{\nu=1}^{N_p} v_{\parallel\nu} \left(w_\nu + \frac{q_s \langle A_{\parallel}^{(n-1)} \rangle}{m_s} \frac{\partial}{\partial v_{\parallel}} F_{0s}(Z_\nu) \zeta_\nu \right) \langle \Lambda_k \rangle_
 u$

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